

# DC6688F2SEN

# Single Battery Operated Microcontroller

DC6688F2SEN is a 8-bit Micro Controller Unit designed with low voltage embedded Flash memory. It is manufactured in advanced CMOS process with turbo mode 80C51 CPU core, Flash program memory, peripherals suitable for battery-operated applications, LCD Monitor, Home Appliance and A/V equipment. As Flash memory is adopted in the MCU, firmware programming and upgrading (In System Programming) can be implemented which can significantly reduce development cycle time and more importantly, inventory burden.

#### **Features**

- ◆ Enhanced 8051 8-bit CPU core, MCS51 instructions compatible
- Power Down and Backup modes
- ◆ Single battery operated (1.2V-1.8V)
- Memory
  - ♦ 2KB Configurable Program & Data Flash Memory
  - Security bit for read back protection
  - ♦ 64B SRAM
- ◆ IR generator by counter A with auto-reload function
- ◆ Built-in transistor for IR LED (I<sub>OL</sub> = 100mA at V<sub>OL</sub> = 0.25V)
- ◆ Two-level priority interrupt controller
- ◆ 16 bit-programmable I/O ports
- ◆ 16-bit Timers x 3
- Low Voltage Detection (LVD) for backup mode
- Maximum operating voltage: 1.8V
- ◆ Operating temperature: -40°C to +85°C
- Package type:
  - ♦ 20-pin TSSOP
  - ♦ 20-pin SSOP
  - ♦ 16-pin SOP

Quick look on Ordering Information

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#### 1 Electrical Characteristics

### 1.1 Absolute Maximum Ratings

(T<sub>A</sub> = 25°C, unless otherwise specified)

Parameter	Symbol	Conditions	Rating	Unit
Supply Voltage	$V_{DD}$	-	-0.3 to +3.8	V
Input Voltage	$V_{IN}$	-	$-0.3$ to $V_{DD} + 0.3$	V
		One I/O pin active[1]	-18	mA
Output Current High	I <sub>ОН</sub>	Total pin current for ports A,B and C[2]	-60	mA
		One I/O pin active[3]	+30	mA
Output Current Low	I <sub>OL</sub>	Total pin current for ports A,B and C[4][5]	+100	mA
Operating Temperature	$T_A$	-	-40 to +85	°C
Storage Temperature	$T_{STG}$	-	-65 to +150	°C

#### Remarks:

- [1] It is measured for any one of I/O pin when configured to push-pull output high.
- [2] It is measured as total for Ports A, B and C when configured to push-pull output high.
- [3] It is measured for any one of I/O pin when configured to push-pull output low.
- [4] It is measured as total for Ports A, B and C when configured to push-pull output low.
- [5] Exclude Port C1 when IR driver is active

### 1.2 Electrostatic Discharge (ESD) Protection Characteristics

Although damage from static discharge is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

Parameter	Symbol	Value	Unit
ESD Target for Machine Model (MM)	V <sub>THMM</sub>	200	V
ESD Target for Human Body Model (MM)	V <sub>THHBM</sub>	2000	V

#### 1.3 DC Electrical Characteristics

 $(T_A = -40$ °C to +85°C,  $V_{DD} = V_{LVD1}$  to 1.8 V)

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Operating Voltage	$V_{DD}$	f <sub>OSC</sub> = 12MHz	$V_{LVD1}$	1	1.8	V
Input High Voltago	$V_{\text{IH1}}$	All input pins except XIN	0.7 V <sub>DD</sub>	-	$V_{DD}$	V
input riigh voitage	$V_{IH2}$	XIN	V <sub>DD</sub> - 0.3	ı	$V_{DD}$	V
Input Low Voltage	V <sub>IL1</sub>	All input pins except XIN	0	ı	0.3 V <sub>DD</sub>	V
input Low Voitage	$V_{IL2}$	XIN	0	-	0.3	V
	V <sub>OH1</sub>	Port C1, V <sub>DD</sub> = 1.3V, I <sub>OH</sub> = - 3mA, T <sub>A</sub> = 25°C	V <sub>DD</sub> - 0.4	-	-	V
Output High Voltage	V <sub>OH2</sub>	Port C0, C2, $V_{DD}$ = 1.3V, $I_{OH}$ = - 1.1mA, $T_A$ = 25°C	V <sub>DD</sub> - 0.4	ı	-	V
	V <sub>OH3</sub>	All output pins except Port C pins, $V_{DD} = 1.3V$ , $I_{OH} = -0.5$ mA, $T_A = 25$ °C	V <sub>DD</sub> - 0.5	ı	-	V
Input High Voltage  Input Low Voltage  Output High Voltage  Output Low Voltage	V <sub>OL1</sub>	Port C1, V <sub>DD</sub> = 1.3V, I <sub>OL</sub> = 6mA, T <sub>A</sub> = 25°C	-	0.3	0.6	V
	V <sub>OL2</sub>	Port C0, C2, $V_{DD} = 1.3V$ , $I_{OL} = 6mA$ , $T_A$	-	0.3	0.6	V

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
		= 25°C				
	V <sub>OL3</sub>	All output pins except Port C pins, $V_{DD} = 1.3V$ , $I_{OL} = 0.5$ mA, $T_A = 25$ °C	-	0.3	0.6	V
Output Low Current IR Transmit	I <sub>OL(IRTX)</sub>	V <sub>OL</sub> = 0.25V, IRDRV = 3, T <sub>A</sub> = 25°C	-	100	-	mA
High Level Output	I <sub>OH(peak)</sub>	V <sub>DD</sub> = 1.5V, peak value	-	-	-10	mA
Current REM	I <sub>OH(avg)</sub>	V <sub>DD</sub> = 1.5V, average value	-	-	-5	mA
Low Level Output	I <sub>OL(peak)</sub>	V <sub>DD</sub> = 1.5V, peak value	-	-	2	mA
Current REM	I <sub>OL(avg)</sub>	V <sub>DD</sub> = 1.5V, average value	-	-	1	mA
Input High Leakage	I <sub>LIH1</sub>	All input pins except XIN, XOUT and ISPSEL, $V_{IN} = V_{DD}$	-	-	1	μΑ
Current	I <sub>LIH2</sub>	XIN and XOUT, V <sub>IN</sub> = V <sub>DD</sub>	-	-	20	μΑ
	I <sub>LIH3</sub>	ISPSEL, V <sub>IN</sub> = V <sub>DD</sub>	-	-	100	μΑ
Input Low Leakage	I <sub>LIL1</sub>	All input pins except XIN and XOUT, $V_{IN} = 0$	-	-	-1	μΑ
Current	I <sub>LIL2</sub>	XIN and XOUT, V <sub>IN</sub> = 0	-	-	-20	μΑ
Output High Leakage Current	I <sub>LOH</sub>	All output pins, V <sub>OUT</sub> = V <sub>DD</sub>	-	-	1	μΑ
Output Low Leakage Current	I <sub>LOL</sub>	All output pins, V <sub>OUT</sub> = 0V	-	-	-1	μΑ
Pull-up Resistors	R <sub>PU</sub>	$V_{DD} = 1.5V, V_{IN} = 0 V; T_A = 25$ °C	75	150	300	kΩ
Supply Current Run Mode[1]	Idd(op)	f <sub>OSC</sub> = 4MHz, V <sub>DD</sub> = 1.5V, T <sub>A</sub> = 25°C	-	1	1.5	mA
Supply Current Power Down Mode[2]	Idd(pd)	V <sub>DD</sub> = 1.5V, T <sub>A</sub> = 25°C	-	1	1.5	μΑ

#### Remarks:

- a) Port A output open-drain.
- b) Port B and CO, C2 input enable pull-up resistor.
- c) Port C1 output push-pull.

## 1.4 Low Voltage Detect circuit Characteristics

 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C)$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Hysteresis Voltage of LVD (slew rate of LVD)	ΔV[1]		-	100	-	mV
Low Voltage Detect Level	$V_{LVD1}$	T <sub>A</sub> = 25°C	1.1	1.15	1.2	V

Remarks:

[1]  $V_{LVD2} - V_{LVD1} = \Delta V$ 

### 1.5 SRAM Data Retention Voltage in Power Down Mode

 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C)$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Data Retention Supply Voltage	$V_{DDDR}$		1.0	-	1.8	V
Data Retention Supply Current	I <sub>DDDR</sub>	V <sub>DDDR</sub> = 1.0V Stop Mode	-	-	1	uA

<sup>[1]</sup> Supply current does not include current drawn through internal pull-up resistors or external output current loads, and is tested if the condition is that all ports configured to output push-pull.

<sup>[2]</sup> Supply current is tested if the condition is that:

### 1.6 Input/Output Capacitance

 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C, V_{DD} = 0 \text{ V})$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Input Capacitance	C <sub>IN</sub>	£ 10411				
Output Capacitance	C <sub>OUT</sub>	f = 1MHz; unmeasured pins are connected to V <sub>ss</sub>	-	-	10	pF
I/O Capacitance	C <sub>IO</sub>	connected to v <sub>SS</sub>				

### 1.7 Flash Memory Data Retention

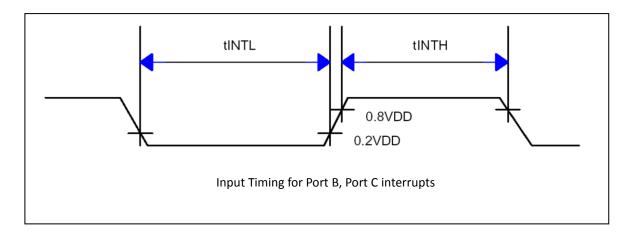
 $(V_{DD} = 1.5V, T_A = 25^{\circ}C)$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
	t <sub>DRP1</sub>	1 write/erase cycle	-	100	-	Year
Data Retention	t <sub>DRP2</sub>	10k write/erase cycle	-	10	-	Year
	t <sub>DRP3</sub>	100k write/erase cycle	-	1	-	Year

#### 1.8 A.C. Electrical Characteristics

 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C)$ 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
Interrupt Input High,	t <sub>INTH</sub> ,	$PBO - PB3$ , $PB7$ , $PC0$ , $PC2$ , $V_{DD} =$	0	_	_	
Low width for Port A	t <sub>INTL</sub>	1.5V	U	-	-	-



### 1.9 Oscillation Characteristics

 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C)$ 

Oscillator	Clock Circuit	Conditions	Min	Тур	Max	Unit
Crystal	C1 XIN XOUT C2	CPU clock oscillation frequency	1	-	4	MHz
Ceramic	C1 XIN XOUT C2	CPU clock oscillation frequency	1	ı	4	MHz
External Clock	External Clock XIN Open Pin XOUT	X <sub>IN</sub> input frequency	1	-	4	MHz

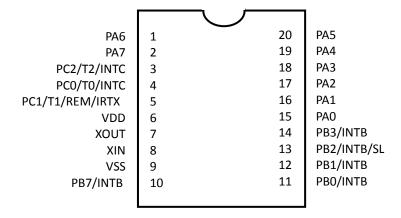
 $(T_A = -40^{\circ}C \text{ to } +85^{\circ}C, V_{DD} = 1.5V)$ 

Parameter	Conditions	Min	Тур	Max	Unit
Crystal	f <sub>OSC</sub> > 1MHz Oscillation stabilization occurs when V <sub>DD</sub>	-	-	20	ms
Ceramic	is equal to the minimum oscillator voltage range	-	-	10	ms
External Clock	$X_{IN}$ input High and Low width( $t_{XL}$ , $t_{XH}$ )	25	-	500	ns
Oscillator Stabilization	tWAIT when released by internal reset[1]	-	2 <sup>12</sup> /f <sub>osc</sub>	-	ms
Wait Time	tWAIT when released by an external interrupt[2]	-	2 <sup>12</sup> /f <sub>osc</sub>	1	ms

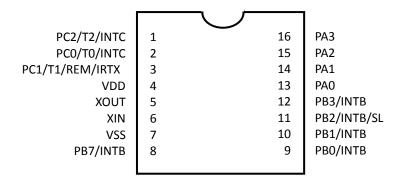
#### Remarks:

## 2 Pin Assignment

(TSSOP20/SSOP20)



(SOP16)



<sup>[1]</sup> f<sub>osc</sub> is the oscillator frequency.

<sup>[2]</sup> The duration of the oscillation stabilization time(tWAIT) when it is released from power down mode by Port B/Port C interrupt.

TSSOP20 SSOP20	SOP16	Pin Name	Symbol	Function
7	5	XOUT	XOUT	Crystal / oscillator output
8	6	XIN	XIN	Crystal / oscillator input
6	4	VDD	VDD	Power
9	7	VSS	VSS	Ground
15	13	PA0	PA0	Configurable input or output port
16	14	PA1	PA1	Configurable input or output port
17	15	PA2	PA2	Configurable input or output port
18	16	PA3	PA3	Configurable input or output port
19	-	PA4	PA4	Configurable input or output port
20	-	PA5	PA5	Configurable input or output port
1	-	PA6	PA6	Configurable input or output port
2	-	PA7	PA7	Configurable input or output port
11 9	PB0/INTB	PB0	Configurable input or output port	
		INTB	Port interrupt input	
12	12 10	PB1/INTB	PB1	Configurable input or output port
12	10		INTB	Port interrupt input
		PB2/INTB/SL	PB2	Input port
13	11		INTB	Port interrupt input
			SL	SL (Single Line) communication signal
14	12	PB3/INTB	PB3	Configurable input or output port
14	12	ר ט אווו ו ס	INTB	Port interrupt input
10	8	PB7/INTB	PB7	Configurable input or output port
10	0	PD//IIVID	INTB	Port interrupt input
			PC0	High current drive configurable I/O
4	2	PCO/TO/INTC	T0	Timer 0 external counter input
			INTC	Port interrupt input
		PC1/T1/REM	PC1	High current drive configurable I/0
5	3		T1	Timer 1 external counter input
			REM	Counter A carrier frequency output
			IRTX	IR transmit with built-in transistor
	1	1 PC2/T2/INTC	PC2	High current drive configurable I/0
3			T2	Timer 2 external counter input
			INTC	Port interrupt input

## 3 **Description**

DC6688F2SEN is an 8-bit Microcontroller Unit designed with low voltage embedded Flash memory. It is manufactured in advanced CMOS process with 8051 CPU core, Flash memory, and peripherals suitable for battery-operated, LCD Monitor, Home Appliance and A/V equipment. As Flash memory is adopted in the MCU, firmware programming and upgrading (In System Programming) can be implemented which can significantly reduce development cycle time and dead inventory.

Highly reliable, low voltage operated Flash memory block is designed and embedded as program or data memory. User can design the chips for different kind of models and applications without worrying problems about long mask ROM cycle time, inventory burden, end customers rescheduling and product end of life. In addition, the program memory can be accessed by a simple external serial bus and therefore, In System Programming (ISP) can be implemented into the target system easily where late programming, upgrade or even model change are possible even after product assembly.

The chip is equipped with dedicated carrier frequency generator (Counter A) and built-in transistor for IR remote controller application. Power management circuits such as the idle mode, power down mode and back up mode, working with the low voltage detection circuit, make the chips perfect for battery-operated, handheld devices.

### 4 Memory

Memory comprises of the following elements, namely:

- ◆ 2KB Program Flash memory + Data Flash memory
- ◆ 64B Internal SRAM
- 128B Special function register (SFR)
- 256B External special function register (XFR)

#### 4.1 Program & Data Flash Memory

A 2K bytes on-chip program Flash is provided for simple application. It can be programmed by In-System-Programming (ISP) method.

In addition, write protection signature is available to avoid writing accidentally.

### 4.2 Special Function Register (SFR)

All memory mapped SFRs, except the program counter and the four 8-register banks, resides in the special function register address space. These registers include arithmetic registers, pointers, I/O-ports, registers for the interrupt system, timers, watchdog timer, etc. Some locations in the SFR address space are addressable as bits.

### 4.3 External Function Register (XFR)

The external function register (XFR) is 256-byte memory area that is logically located in the built-in memory space. This is accessed like external RAM (MOVX instructions). This area is reserved for controlling and accessing the on-chip peripherals additional to standard 8051 core.

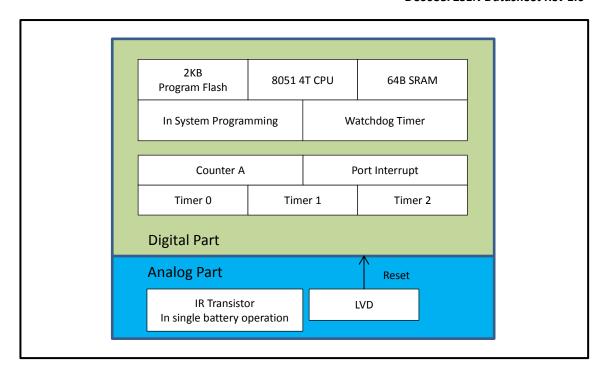
#### 5 Architecture

With the 4T 8051 8-bit CPU, instruction execution time is 500ns at 8Mhz operating frequency. Such high performance CPU provides an option for system design to use slow system clock in order to lower the overall operating power consumption which is important to all battery-operated products.

Highly reliable, low voltage operated Flash memory block is designed and embedded into the chips for both program memory and user data memory. User can design the chips for different kind of models and applications without worry problems about long mask ROM cycle time, inventory burden, end customers rescheduling and product end of life. In addition, the program memory can be accessed by a simple external serial bus and therefore, In System Programming (ISP) can be implemented into the target system easily where late programming, upgrade or even model change are possible even after production assemble. The built-in data Flash memory can be used to store real time user data and the function is just same as EEPROM.

The block diagram is illustrated in the following figure.

8



### 6 Central Processing Unit (CPU)

The 4T 8051 CPU (Central Processing Unit) is MCS51 instruction compatible. It consists of the instruction decoder, the arithmetic section and the program control section. Each program instruction is decoded by the instruction decoder. This unit generates the internal signals controlling the functions of the individual units within the CPU. They have an effect on the source and destination of data transfers and control the ALU processing.

The arithmetic section of the processor performs extensive data manipulation and is comprised of the arithmetic/logic unit (ALU), A register, B register and PSW register. The ALU accepts 8-bit data words from one or two sources and generates an 8-bit result under the control of the instruction decoder. The ALU performs the arithmetic operations add, subtract, multiply, divide, increment, decrement, BDC-decimal-add-adjust and compare, and the logic operations AND, OR, Exclusive OR, complement and rotate (right, left or swap nibble (left four)). Also included is a Boolean processor performing the bit operations as set, clear, complement, jump-if-not-set, jump-if-set-and-clear and move to/from carry. Between any addressable bit (and its complement) and the carry flag, it can perform the bit operations of logical AND or logical OR with the result returned to the carry flag.

The program control section controls the sequence in which the instructions stored in program memory are executed. The 16-bit program counter (PC) holds the address of the next instruction to be executed. The conditional branch logic enables internal and external events to the processor to cause a change in the program execution sequence.

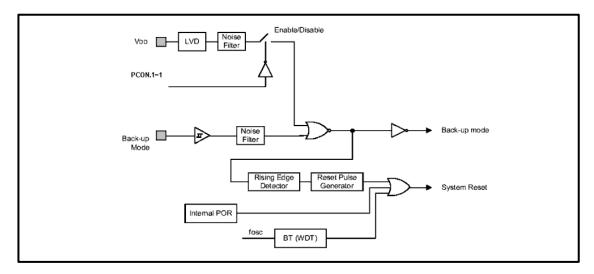
## 7 Low Voltage Detection Reset

The on-chip Low Voltage Detect circuit generates a system reset. It detects the level of  $V_{DD}$  by comparing the voltage at pin  $V_{DD}$  with reference voltage,  $V_{LVD1}$  (Low Voltage Detect Voltage Level 1). Whenever the voltage at  $V_{DD}$  is falling down and passing  $V_{LVD1}$ , the IC goes into back-up mode at the moment " $V_{DD} = V_{LVD1}$ ".

On the other hand, system reset pulse is generated by the rising slope of V<sub>DD</sub>. While the voltage at pin

 $V_{DD}$  is rising up and passing  $V_{LVD2}$  (Low Voltage Detect Voltage Level 2), the reset pulse is occurred at the moment " $V_{DD} >= V_{LVD2}$ ".

LVD provides a hysteresis ( $V_{LVD2}-V_{LVD1}$ ) to avoid the oscillation near the decision level. For the sake of reducing the current consumption, this function can be disabled when the IC is in power down mode.

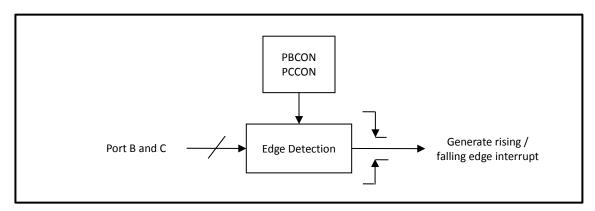


### 8 **I/O port**

The 20-pin package has one 8-bit port (PA), one 4-bit port (PB) and one 3-bit port (PORTC). All ports are latches used to drive the bi-directional I/O lines. On reset, Port A and Port B are set to the value (11111111). Port C is set to the value (00001101).

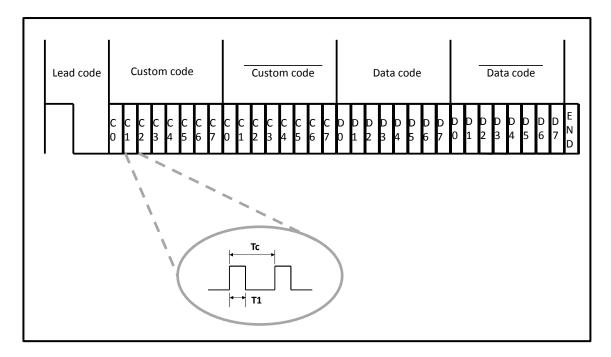
The 16-pin package has one 4-bit port (PA), one 4-bit port (PB) and one 3-bit port (PORTC). All ports are latches used to drive the bi-directional I/O lines. On reset, Port A and Port B are set to the value (11111111). Port C is set to the value (00001101).

Port interrupt function is supported for port B and C. Pull-up resistors are also included and could be assigned pin-by-pin by programming the pull-up resistor enable register.



## 9 Counter A (IR Carrier Frequency Generator)

Counter A is a 16-bit counter. It can be used to generate the carrier frequency of remote controller.



Counter A can also be used as PWM counter with two 8-bit data registers. It supports 5-8 bit mode selection and 1-128 clock division selection.

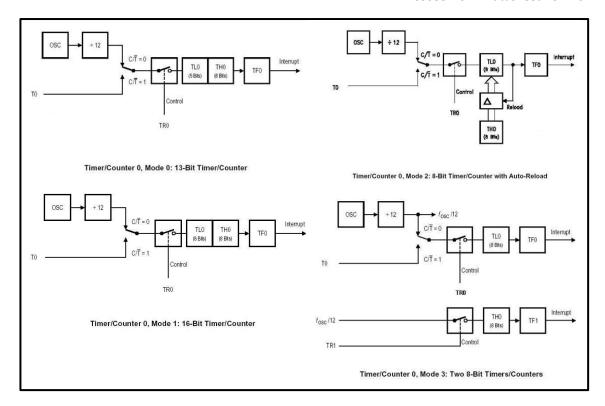
### 10 General Purpose Timers/Counters

Three independent general purpose 16-bit timers/counters, Timer0, Timer1 and Timer2 are integrated for use in counting events, and causing periodic (repetitive) interrupts. Either can be configured to operate as timer or event counter. In the 'timer' function, the registers TLx and/or THx (x = 0, 1) are incremented once every machine cycle. Thus, one can think of it as counting machine cycles.

Regarding the 'counter' function, the registers TLx and/or THx (x = 0, 1) are incremented in response to a 1-to-0 transition at its corresponding external input pin, T0 or T1. In this function, the external input is sampled during every machine cycle. When the samples show a high in one cycle and a low in the next cycle, the count is incremented. The new count value appears in the register during the cycle following the one in which the transition was detected. Since it takes 2 machine cycles (24 oscillator periods) to recognize a 1-to-0 transition, the maximum count rate is 1/24 of the oscillator frequency. There are no restrictions on the duty cycle of the external input signal, but to ensure that a given level is sampled at least once before it changes, it should be held for at least one full machine cycle.

Timer 2 has several features on top of Timer 0 and 1. It runs in 16-bit mode.

- 16-bit timer/counter
- 16-bit timer with capture
- 16-bit auto-reload timer/counter with up/down count
- Timer output generator



## 11 In System Programming

The In System Programming (ISP) feature allows the update of Flash program memory content when the chip is already plugged on the application board. It requires only 3 wires to minimize the number of added components and board area impact.

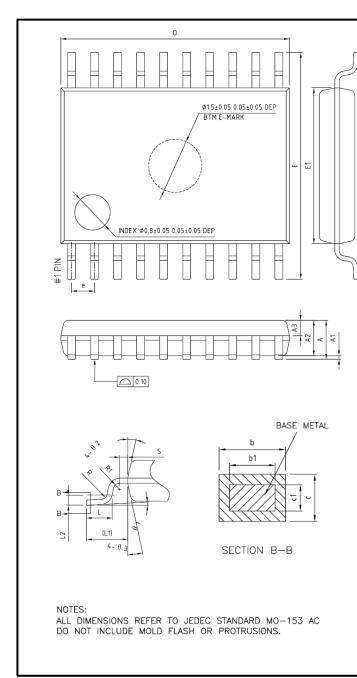
# 12 Ordering Information

Part No	Package	Program Flash	Data Flash	SRAM	1/0
DC6688F2SEN	TSSOP20	2KB	-	64B	16
DC6688F2SEN-TR1	TSSOP20[1]	2KB	-	64B	16
DC6688F2SENP	SSOP20	2KB	-	64B	16
DC6688F2SENP-TR1	SSOP20[1]	2KB	-	64B	16
DC6688F2SEK	SOP16	2KB	-	64B	12

[1] Tape and reel packing.

# 13 Package Outlines

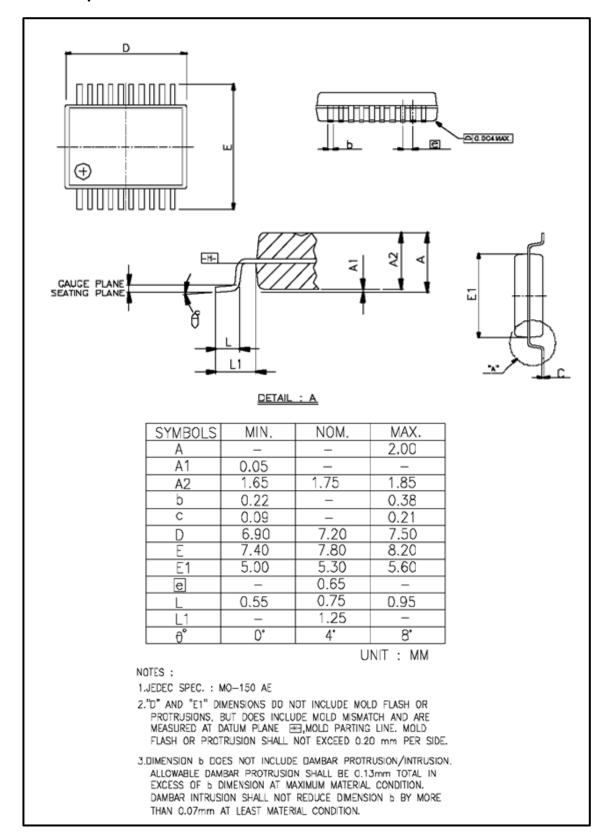
### 13.1 20-pin TSSOP



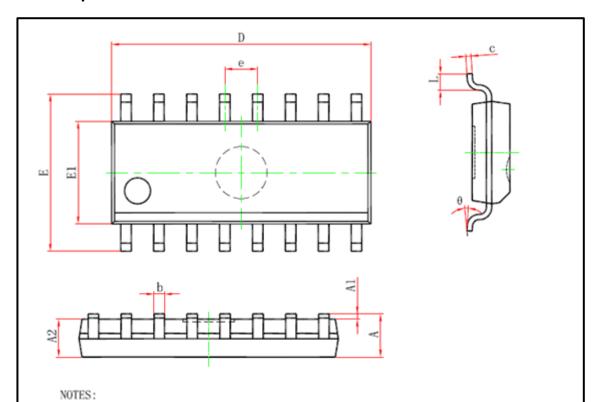
COMMON DIMENSIONS
(UNITS OF MEASURE=MILLIMETER)

SYMBOL	MIN	NOM	MAX	
Α	_	_	1.20	
A1	0.05	_	0.15	
A2	0.90	1.00	1.05	
A3	0.34	0.44	0.54	
b	0.20	_	0.28	
b1	0.20	0.22	0.24	
С	0.10	_	0.19	
c1	0.10	0.13	0.15	
D	6.40	6.50	6.60	
E	6.20	6.40	6.60	
E1	4.30	4.40	4.50	
е	0.65BSC			
L	0.45	0.60	0.75	
L1		1.00REF		
L2		0.25BSC		
R	0.09	_	_	
R1	0.09	_	_	
S	0.20	_	_	
θ 1	0°	_	8°	
θ 2	10°	12°	14°	
θ 3	10°	12°	14°	

#### 13.2 20-pin SSOP



### 13.3 16-pin SOP



ALL DIMENSIONS MEET JEDEC STANDARD MS-012 AC DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.

Symbol	Dimensions In Millimeters		Dimensions In Inches		
Symoor	Min	Max	Min	Max	
A		1.750		0.069	
A1	0.100	0.250	0.004	0.010	
A2	1.400	1.500	0.055	0.059	
b	0.330	0.510	0.013	0.020	
С	0.170	0.250	0.007	0.010	
D	9.800	10.200	0.386	0.402	
e	1.270 (BSC)		0.050 (BSC)		
E	5.800	6.200	0.228	0.244	
E1	3.800	4.000	0.150	0.157	
L	0.400	1.270	0.016	0.050	
θ	0°	8°	0°	8°	

# **14 Revision History**

Document Rev No.	Issued Date	Section	Page	Description	Edited by	Reviewed by
0.9	Feb, 2012	-	-	Preliminary release	Celia Ki	Danny Ho
0.9a	April, 2012	-	-	Revise the Idd measuring condition to VDD=1.5V	Celia Ki	Danny Ho
1.0	March, 2013	-	-	Update for new features: Remove UART and SPI section	Celia Ki	Danny Ho
1.3	May, 2014	-	-	Add IR Transistor configuration	Celia Ki	Danny Ho
1.4	March, 2014	-	-	Change the operating voltage	Philip Hung	Fred Law
1.5	April, 2014	-		Add SOP 16 package	Philip Hung	Eddy Cheung
1.6	May, 2014	-	-	Release new format	Philip Hung	Kennis To

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